

# (Visualizing) Plausible Dynamic Treatment Effect Paths

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# The goal

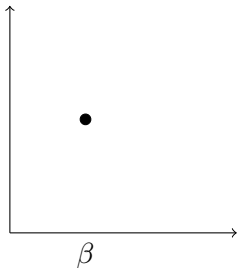
- ▶ We are interested in the dynamic treatment effect path of a policy.
- ▶ Examples include
  1. Dynamic treatment effects in microeconomics (distributed lag models),
  2. Impulse response functions in macroeconomics (local projections),
  3. Event study paths in finance (event studies).

# Notation

- ▶ Let  $\beta = \{\beta_h\}_{h=1}^H$  be the parameter of interest.
- ▶  $\beta_h$  corresponds to treatment effect at horizon  $h$ .
- ▶ We have access to jointly normal estimates  $\hat{\beta} = \{\hat{\beta}_h\}_{h=1}^H$ .

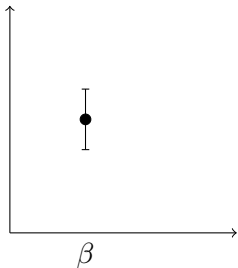
# A primer on uncertainty quantification

# Quantifying uncertainty



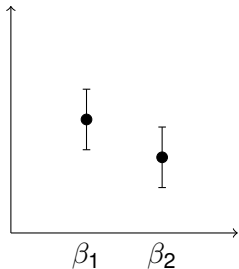
- ▶ Single parameter of interest  $\beta$ .
- ▶ Standard approach is to construct confidence interval.
- ▶ Coverage is  $(1 - \alpha)$ :  $\mathbb{P}(\ell(X) < \beta < u(X)) = 1 - \alpha$ .
- ▶ Intuitively: values inside CI appear “plausible”

# Quantifying uncertainty



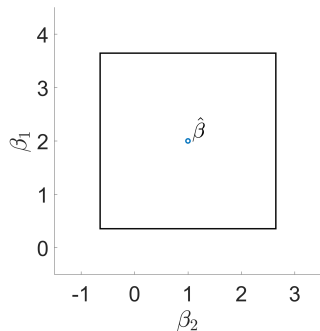
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# Quantifying uncertainty



- ▶ Standard confidence intervals are pointwise valid.
- ▶  $(\ell(X), u(X)) : \mathbb{P}(\ell_h(X) < \beta_h < u_h(X)) = 1 - \alpha$ .
- ▶ NOT uniformly valid.
- ▶ For example, with  $\text{Cov}(\hat{\beta}_k, \hat{\beta}_l) = 0$ :  
 $\mathbb{P}(\ell_h(X) < \beta_h < u_h(X) \forall h) = (1 - \alpha)^H$ .

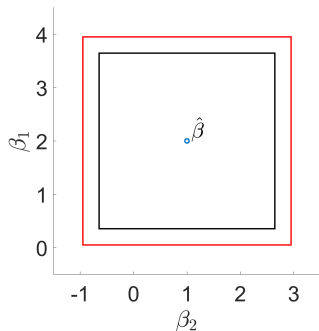
## In two dimensions



- Fix  $\alpha = 0.1$ ,  $\text{Cov}(\hat{\beta}_1, \hat{\beta}_2) = 0$ .
- Pointwise CIs:  
 $(\ell(X), u(X)) : \mathbb{P}(\ell_h(X) < \beta_h < u_h(X)) = 0.9$ .
- $\mathbb{P}(\ell(X) < \beta < u(X)) = 0.9^2 = 0.81$ .
- $\mathbb{P}(\beta \in CR^{\text{pointwise}}) = 0.81$ .

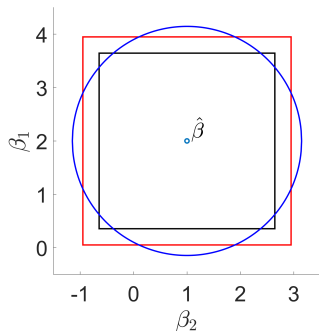


## In two dimensions



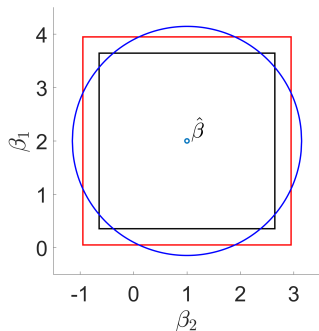
- Fix  $\alpha = 0.1$ ,  $\text{Cov}(\hat{\beta}_1, \hat{\beta}_2) = 0$ .
- sup-t CIs:  $(\ell(X), u(X)) : \mathbb{P}(\ell_h(X) < \beta_h < u_h(X)) \approx 0.949$ .
- $\mathbb{P}(\ell(X) < \beta < u(X)) = 0.9$ .
- $\mathbb{P}(\beta \in \textcolor{red}{CR}^{\text{sup-t}}) = 0.9$ .

## In two dimensions



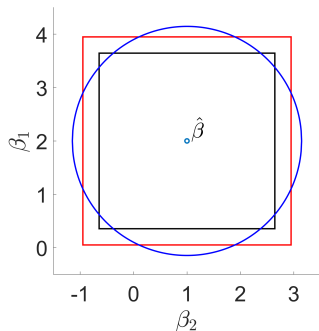
- Fix  $\alpha = 0.1$ ,  $Cov(\hat{\beta}_1, \hat{\beta}_2) = 0$ .
- Wald confidence region: the set of  $\beta$  for which a joint F-test of the observed point estimates is not rejected.
- $\mathbb{P}(\beta \in CR^{Wald}) = 0.9$ .

# Comments



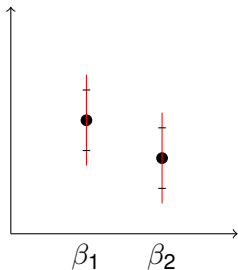
- ▶ Many other confidence regions exist.
- ▶ Both  $CR^{sup-t}$  and  $CR^{Wald}$  depend on off-diagonal entries in  $Var(\beta)$ . [Example](#)
- ▶ Power against different alternatives.
- ▶  $CR^{Wald}$  infeasible to visualize in higher dimensions.

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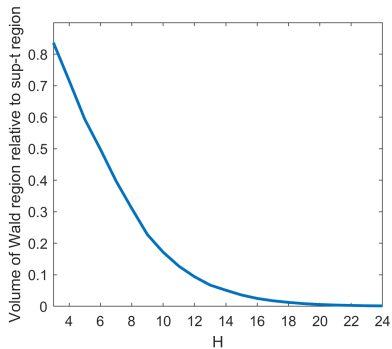
# Quantifying uncertainty



- ▶  $CR^{sup-t}: (\ell_k(X), u_k(X))$ .
- ▶  $(\ell_h(X), u_h(X)) : \beta_h \pm c^{sup-t} \sigma_{\beta_h}$ .
- ▶  $\mathbb{P}(\beta \in CR^{sup-t}) = 1 - \alpha$ .

cf. Freyberger and Rai (2018); Montiel Olea and Plagborg-Møller (2019); Callaway and Sant'Anna (2021); Jorda (2023); Boxell, Gentzkow, and Shapiro (2024); Mogstad, Romano, Shaikh, and Wilhelm (2024)

# In higher dimensions



- ▶ Volume of  $CR^{sup-t}$  explodes relative to  $CR^{Wald}$ .
- ▶ Implication: vast majority of paths inside  $CR^{sup-t}$  rejected by a joint test.
- ▶ Suppose we uniformly draw paths from  $CR^{sup-t}$  for  $\alpha = 0.05$ .  
At  $H = 24$ , 99.9% of paths rejected by a joint test!

# This paper

- ▶ We propose two types of plausible bounds that are
  - a) feasible to add to a standard plot.
  - b) (in general) narrower than existing confidence bands.
- 1. Restricting functional forms in data-driven way to "reasonable shapes" (Restricted Plausible Bounds).
- 2. Relaxing uniformity requirement (Averaged Plausible Bounds).

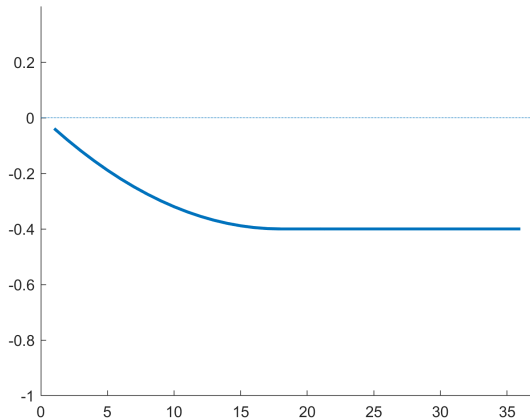
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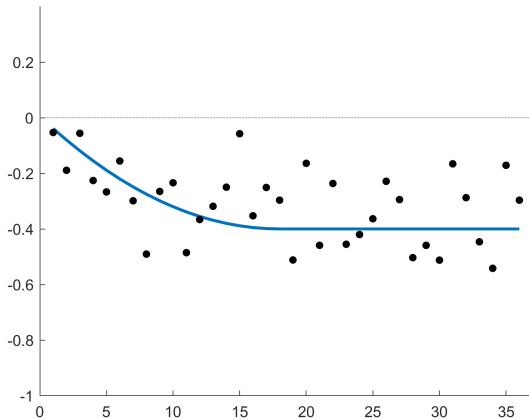
## Restricted Plausible Bounds

## An example



► Blue : true treatment effect  $\beta$ .

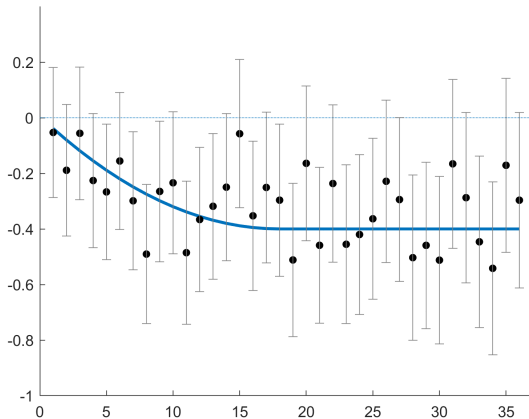
# An example



► Black dots: estimates  $\hat{\beta}$ .

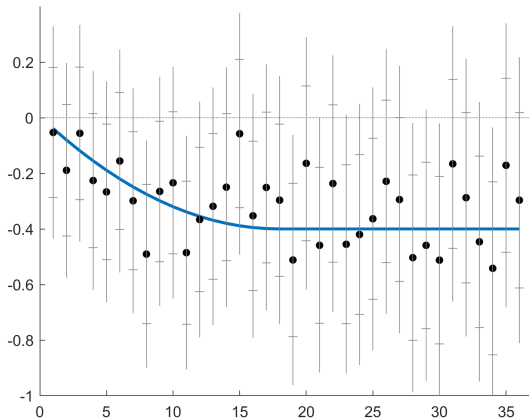
►  $\hat{\beta}_h \stackrel{i.i.d.}{\sim} N(\beta_h, \sigma_h)$ .

## An example



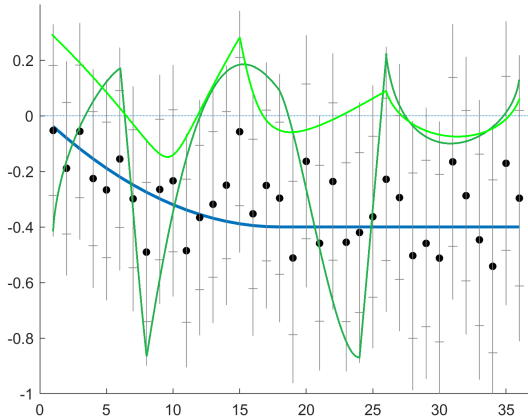
► Intervals: pointwise confidence intervals for  $\beta_h$ .

## An example



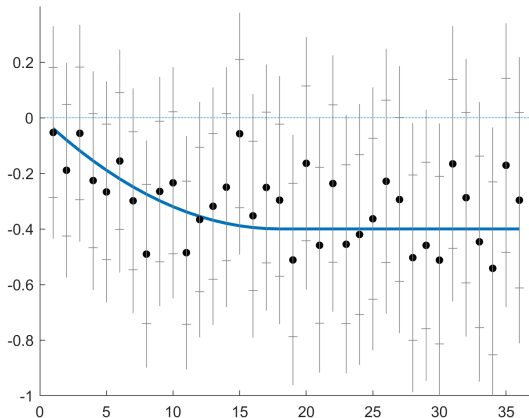
- Set of outer lines: sup-t confidence bands.

# Uninformative data?



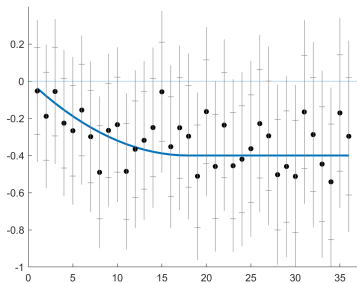
- Many paths with different overall effect or different shape appear “plausible”.

# Uninformative data?



► Note: 1 out of 100,000 uniformly drawn paths in  $CR^{sup-t}$  not rejected by joint test.

# Uninformative data?

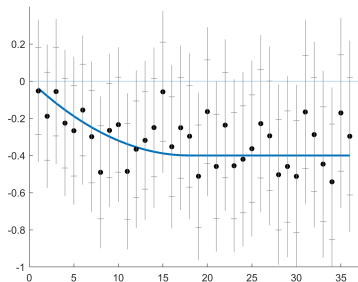


Restricting degrees of freedom:

- ▶ Parametric model for  $\beta$  (e.g. effect grows linearly)
- ▶ time aggregation (e.g. monthly to quarterly). Restricts  $\beta$  to “step function”.
- ▶ estimate via VAR: Restricting to functional forms compatible with chosen VAR.
  - ▶  $AR(1) \Rightarrow \beta_h = \rho^h$ .

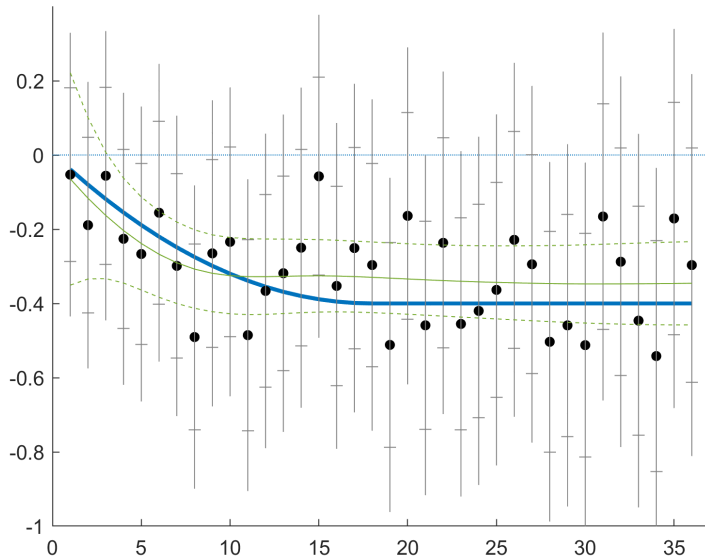


# Uninformative data?

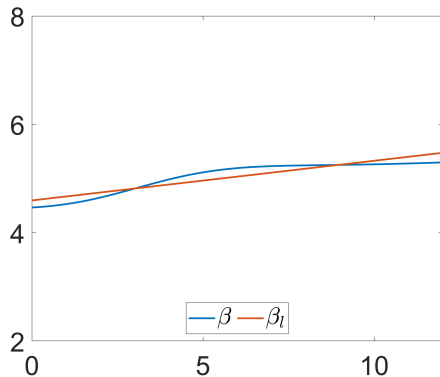
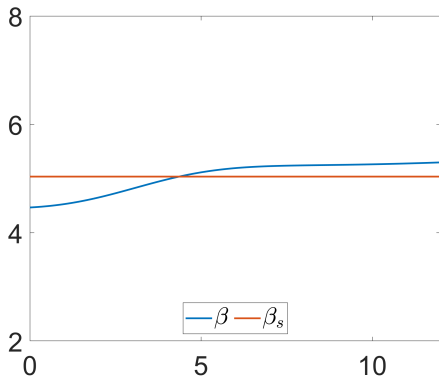


- Our proposal: transparent, data-driven restrictions on  $\beta$ .
- Economic intuition: smooth + eventually flat.

# Restricted plausible bounds



## A toy example (two surrogate models)



►  $\beta_s = \arg \min_b \|\beta - b\|$  s.t.  $\Delta b = 0$

► model with constant treatment effect

►  $\beta_l = \arg \min_b \|\beta - b\|$  s.t.  $\Delta^2 b = 0$

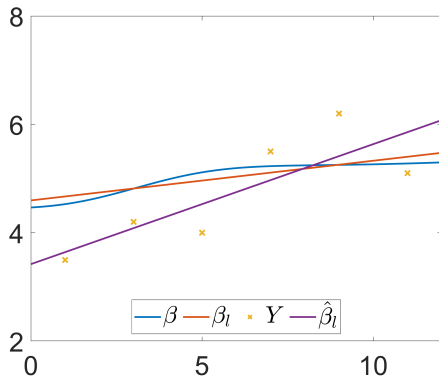
► model with linear treatment effect

## A toy example

- ▶ If model  $M$  is fixed, inference for surrogate  $\beta_M$  is easy.
- ▶ E.g., model with linear treatment effect:

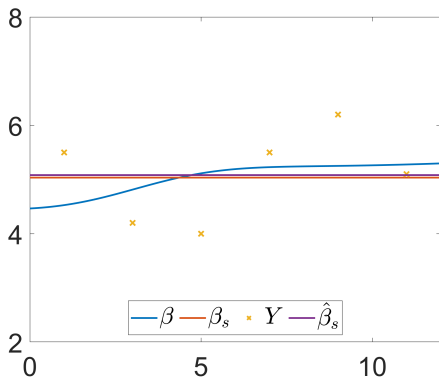
$$\hat{\beta}_l = \arg \min_b \|Y - b\| \text{ s.t. } \Delta^2 b = 0$$

- ▶ CIs for  $\beta_l$  follow (not  $\beta$ !).

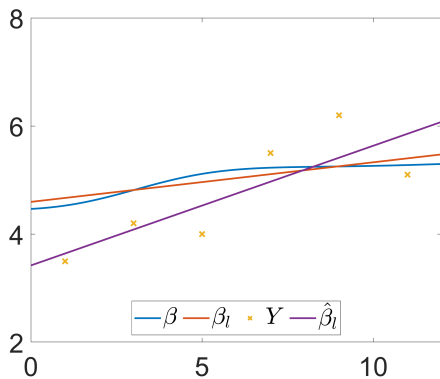


## A toy example

If model  $M(Y)$  depends on the data, this creates a problem.



$M = s$  if realization of  $Y_1$  is large



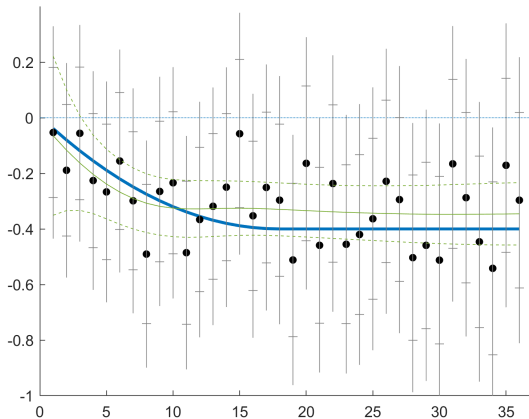
$M = l$  if realization of  $Y_1$  is small

## Restricted plausible bounds (toy example)

Our proposal: CR for  $\beta_{M(Y)}$ :  $M$  explicitly random, function of data

- ▶ Use data to select degrees of freedom/degree of smoothness (e.g.  $\beta_I$  or  $\beta_S$ ).
- ▶ Take into account model uncertainty to construct uniformly valid CR for selected surrogate.

## An example



- ▶ three degrees of freedom
- ▶ chosen using the data

# Restricted plausible bounds

Let  $\hat{\beta} \sim N(\beta, V_{\beta})$ , where  $\beta$  is a  $H \times 1$  vector.

Define [More details](#)

$$\beta^* = \arg \min_b \underbrace{(\hat{\beta} - b)' V_{\beta}^{-1} (\hat{\beta} - b)}_{\text{distance from } \hat{\beta}} \quad (1)$$

such that  $\underbrace{b' D_1' W_1(K) D_1 b}_{\text{small first difference, after horizon K}} < c_1$  and  $\underbrace{b' D_3' W_2 D_3 b}_{\text{small third difference}} < c_2 .$

- ▶ “treatment path is eventually flat.”
- ▶ “treatment path is smooth.”



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(1)

- ▶ “treatment path is eventually flat.”
- ▶ “treatment path is smooth.”

# Restricted plausible bounds

Equivalently,

$$\begin{aligned}\beta^* &= \arg \min_b Q(b, \lambda_1, \lambda_2, K) \\ &= \arg \min_b \underbrace{(\hat{\beta} - b)' V_{\beta}^{-1} (\hat{\beta} - b)}_{\text{distance from } \hat{\beta}} + \lambda_1 \underbrace{b' D_1' W_1(K) D_1 b}_{\text{penalty on first difference after horizon K}} + \lambda_2 \underbrace{b' D_3' W_2 D_3 b}_{\text{penalty on third difference}}\end{aligned}$$

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- ▶ “treatment path is smooth.”

## Restricted plausible bounds

$$\begin{aligned}\beta^* &= \arg \min_b Q(b, \lambda_1, \lambda_2, K) \\ &= \arg \min_b \underbrace{(\hat{\beta} - b)' V_{\beta}^{-1} (\hat{\beta} - b)}_{\text{distance from } \hat{\beta}} + \lambda_1 \underbrace{b' D_1' W_1(K) D_1 b}_{\text{penalty on first difference after horizon K}} + \lambda_2 \underbrace{b' D_3' W_2 D_3 b}_{\text{penalty on third difference}}\end{aligned}$$

► Closed form solution for  $\beta^*$ :

$$\begin{aligned}\beta^* &= \left( V_{\beta}^{-1} + \lambda_1 D_1' W_1(K) D_1 + \lambda_2 D_3' W_3 D_3 \right)^{-1} V_{\beta}^{-1} \hat{\beta} \\ &= P \hat{\beta}\end{aligned}$$

# Restricted plausible bounds

For fixed  $\lambda_1, \lambda_2, K$  (fixed  $M$ ):

- Distribution for  $\beta^*$ :

$$\beta^* - P\beta \sim N(0, PV_\beta P')$$

- Can construct confidence region for  $\{P\beta_h\}_{h=1}^H$ .
- What is  $P\beta = \beta(\lambda_1, \lambda_2, K)$ ? “Surrogate of  $\beta$ ” [Genovese and Wasserman, 2008] (cf. linear approximation)

# Our proposal

Step 1: Use data to select Model  $M(Y)$  (to select  $\lambda_1$ ,  $\lambda_2$ , and  $K$ ).

- ▶ Tie Researchers' hands by prespecifying  $\mathcal{M}$ , the universe of models considered
- ▶ Choice set includes:
  - ▶ constant treatment effect model ( $df = 1$ )
  - ▶ unrestricted estimates  $\hat{\beta}$  ( $df = H$ )
- ▶ Select model (e.g. degrees of freedom  $df(\lambda_1, \lambda_2, K)$ ) using information criterion.

More details

# Our proposal

Step 2: Construct CR for  $\beta_{M(Y)}$

- ▶ Take into account that model  $M$  is random, function of data
- ▶ Use Valid Post-Selection Inference (Berk et al. [2013]) to create  $CR^{PSI}$ .  
[More details](#)
- ▶  $CR^{PSI}$  is a valid CR for selected surrogate.

# Restricted plausible bounds

## Proposition 1

*For any treatment path  $\beta$ , we obtain valid coverage for its surrogate  $\beta(\lambda_1, \lambda_2, K)$ :*

$$\mathbb{P}[\beta(\lambda_1, \lambda_2, K) \in CR^{POS}] \geq 1 - \alpha. \quad (2)$$

## Proof.

This follows immediately from the POSI guarantees:

$$\mathbb{P}(\beta_M \in CR^{POS} | M(Y) = M) \geq 1 - \alpha).$$



# Restricted plausible bounds

## Proposition 2

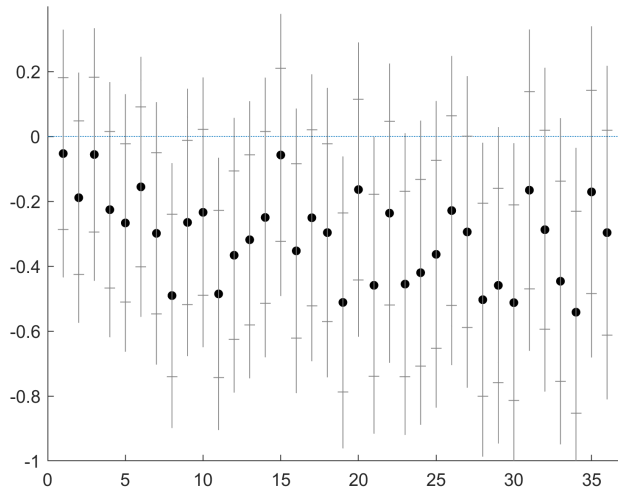
*Suppose  $\mathbb{P}(\beta_{M(Y)} = \beta_M = \beta) = 1$ . Then,*

$$\mathbb{P}(\beta \in CR^{POS}) \geq 1 - \alpha. \quad (3)$$

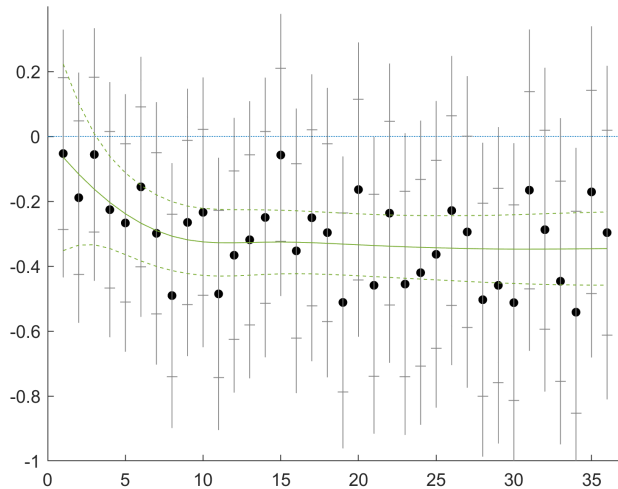
Note: Under some regularity conditions,  $\lim_{V_\beta \rightarrow 0} \mathbb{P}(\beta_{M(Y)} = \beta_M = \beta) = 1$ .



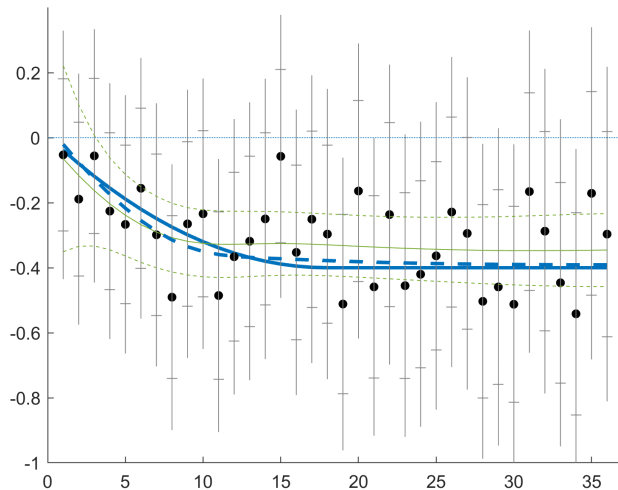
# Example



# Example



# Example



Additional example

Averaged plausible bounds

# Averaged plausible bounds

- ▶ Do not require any functional form restrictions.
- ▶ Relax uniform coverage to a weaker notion of “average coverage”.
- ▶ True treatment paths will be **on average** within our bounds for  $(1 - \alpha)$  of all realizations.

## Averaged plausible bounds

- ▶ Correspond to largest and smallest total treatment effect that is consistent with the data.
- ▶ Boundary paths for testing the cumulative effect of the policy.
- ▶ Denoted by  $\{\tilde{l}b_h, \tilde{u}b_h\}_{h=1}^H$ .

# Averaged plausible bounds

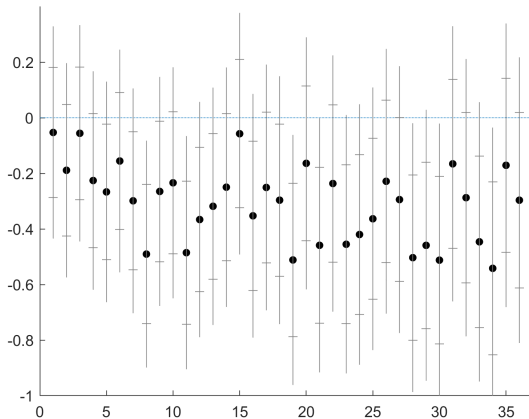
## Proposition 3

*A Wald test on the cumulative treatment effect with significance level  $(1 - \alpha)$  will reject*

- a) *any treatment path  $\tilde{\beta}_h$  with  $\sum_{h=1}^H \tilde{\beta}_h > \sum_{h=1}^H \tilde{u}b_h^{1-\alpha}$ .*
- b) *any treatment path  $\tilde{\beta}_h$  with  $\sum_{h=1}^H \tilde{\beta}_h < \sum_{h=1}^H \tilde{l}b_h^{1-\alpha}$ .*

- Any path that is not, on average, inside our averaged plausible bounds, implies a cumulative treatment effect that is rejected by the corresponding hypothesis test. [More details](#)

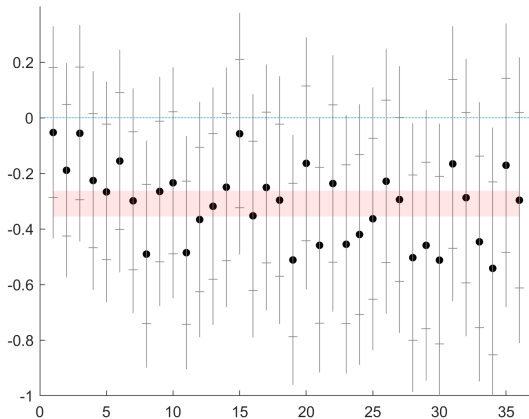
## Estimates too noisy?



- Estimates can appear uninformative based on uniform confidence bands.

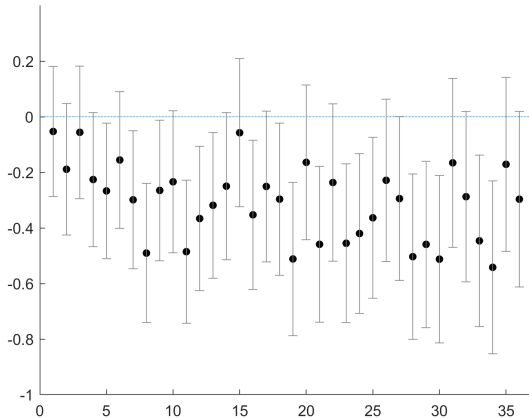


# Averaged plausible bounds



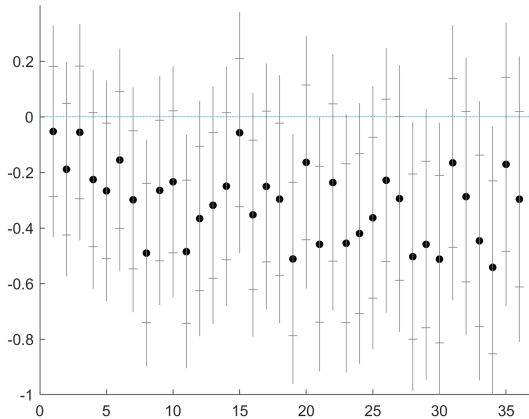
- ▶ Averaged plausible bounds: shaded red area
- ▶ Tight bounds on overall treatment effect

## Summary: traditional figure



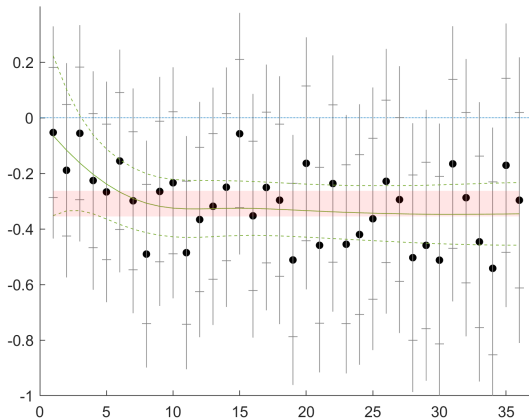
► Includes pointwise valid CIs

## Summary: modern figure



► Includes uniform CR

## Summary: our figure

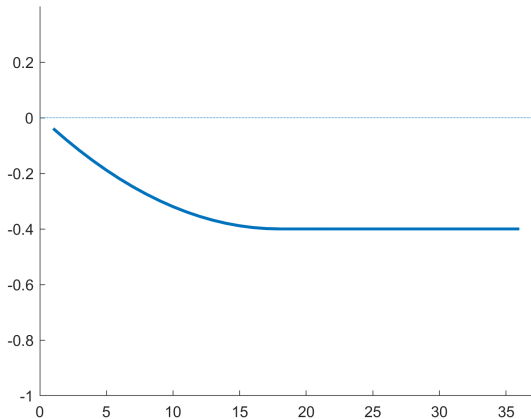


Includes three additional objects:

- ▶ Shaded red area: averaged plausible bounds:
- ▶ Green lines:
  1. Restricted plausible bounds (dashed)
  2. Restricted estimates (solid)

## Numerical Illustrations

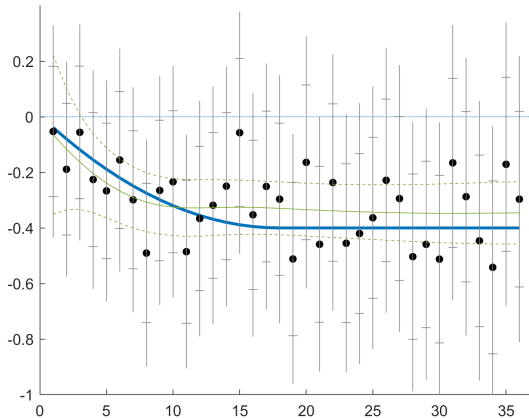
# The setup



► Blue : true treatment effect  $\beta$ .

► Repeated simulations of  $\hat{\beta} \sim N(\beta, V_{\beta})$

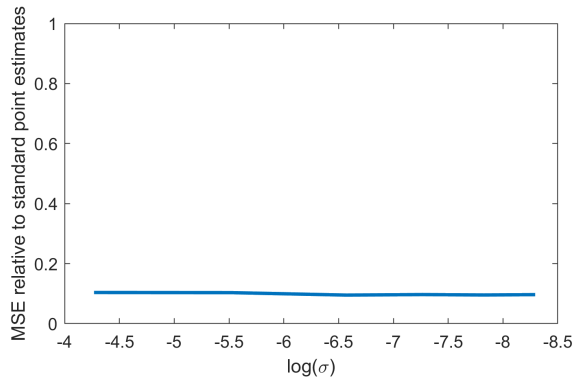
# Estimation (restricted estimator $\hat{\beta}_{M(Y)}$ )



Compare

- Unrestricted estimates  $\hat{\beta}$
- Restricted estimates  $\hat{\beta}_{M(Y)}$

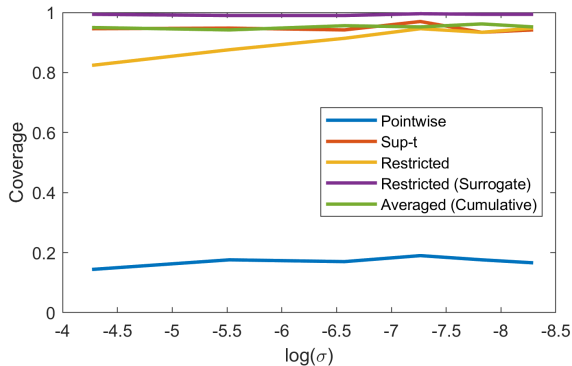
# Estimation (restricted estimator $\hat{\beta}_{M(Y)}$ )



- ▶ Depicted:  $MSE_{\hat{\beta}_{M(Y)}} / MSE_{\hat{\beta}}$
- ▶ Good point estimation properties
- ▶ Large improvement in MSE (cf. James-Stein estimator)



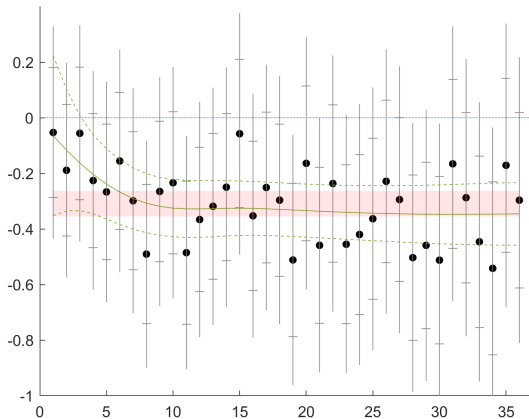
# Inference



Restricted Bounds ( $CR^{POS}$ ):

- Coverage of  $\beta$  approaches 95% as  $n \rightarrow \infty$ .
- Coverage guarantee for  $\beta_M$ .
- Much better than pointwise (Even though tighter!).

# Inference



- ▶ Restricted much narrower than pointwise
- ▶ Much better coverage

# Conclusion

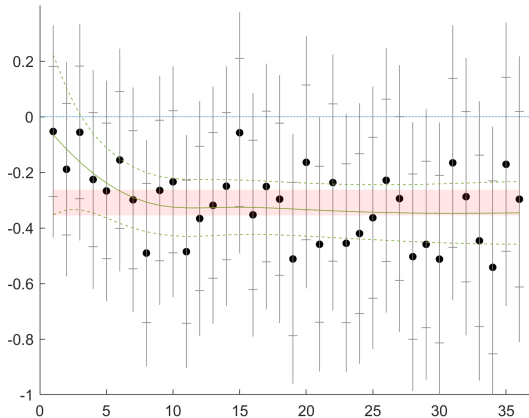
- ▶ We are interested in (joint inference on) the dynamic treatment effect of a policy.
- ▶ We propose two novel types of bounds to include in standard visualizations.
  - ▶ Both bounds can be substantially tighter than standard confidence bands.
  - ▶ Can provide useful insights when traditional confidence bands appear uninformative.
- ▶ Improved point estimation through data-driven smoothing

## Next steps

- ▶ Write the paper.
- ▶ Your thoughts:
  - a) Things you liked?
  - b) Things you didn't like?
  - c) Additional things you'd like to see/discussed?
  - d) Thoughts on naming/framing?
- ▶ Papers that come to mind we could replicate?

Thank you!

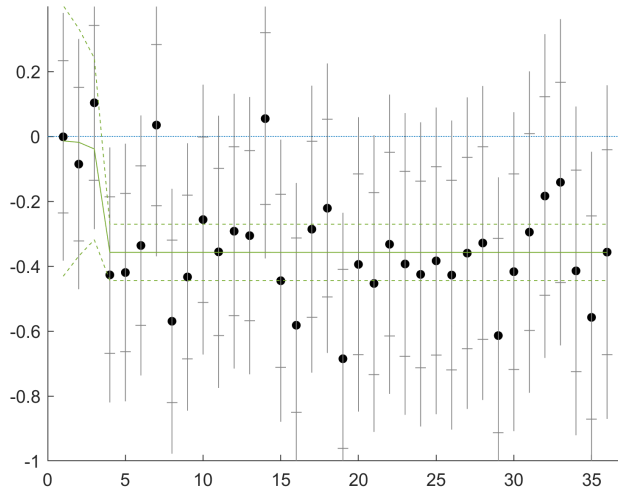
## Summary: our figure



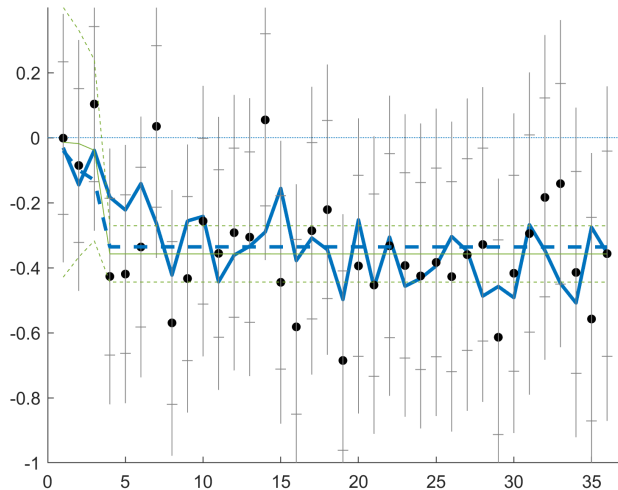
Includes three additional objects:

- ▶ Shaded red area: averaged plausible bounds:
- ▶ Green lines:
  1. Restricted plausible bounds (dashed)
  2. Restricted estimates (solid)

## Example 2



## Example 2





## Averaged plausible bounds

Let

$$ub^{1-\alpha} = \max \sum_{h=1}^H \beta_h^* \quad \text{s.t. } (\beta^* - \hat{\beta})' \Sigma_{\hat{\beta}} (\beta^* - \hat{\beta}) = c^{(1-\alpha)}, \quad (4)$$

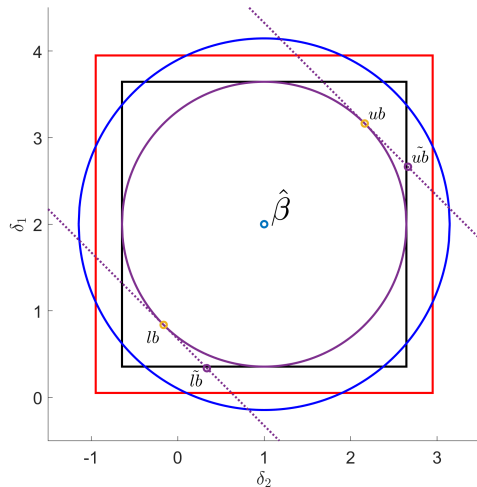
where  $c^{(1-\alpha)}$  denotes the inverse of the chi-square cdf with 1 degree of freedom at chosen significance level  $(1 - \alpha)$ .

- ▶ Define  $lb^{1-\alpha}$  analogously, replacing the max in (4) with min.
- ▶ Closed form solution.

## Averaged plausible bounds

- ▶ Note: Only scalar corresponding to upper and lower limit of cumulative effect is identified
- ▶ Many other ways to visualize. E.g.:
  - ▶ shift point estimates ( $\dot{u}b, \dot{l}b$ )
  - ▶ shift moving average ( $\check{u}b, \check{l}b$ )
  - ▶ **shift constant effects estimate** ( $\tilde{u}b, \tilde{l}b$ )

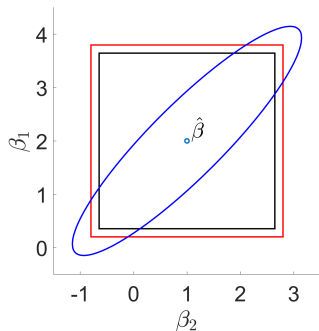
# In two dimensions



- ▶ purple dotted lines give bounds on cumulative effect
- ▶ paths inside these bounds corresponds to paths inside

[back](#)

# Comments



- Suppose  $\text{Cov}(\hat{\beta}_1, \hat{\beta}_2) = 0.9$ .
- Both  $CR^{sup-t}$  and  $CR^{Wald}$  depend on off-diagonal entries in  $\text{Var}(\beta)$ . [back](#)

# Notation

Let  $\hat{\beta} \sim N(\beta, V_\beta)$ , where  $\beta$  is a  $H \times 1$  vector.

- ▶  $D_1$  is first difference maker,  $D_3$  is third difference maker
- ▶  $V_1 = D_1 V_\beta D_1'$ ,  $V_3 = D_3 V_\beta D_3'$  are variance matrices for first and third differences
- ▶  $W_1(K) = \text{diag}(\text{zeros}(K), V_1(K+1 : \text{end}, K+1 : \text{end}) / \text{mean}(\text{diag}(V_1(K+1 : \text{end}, K+1 : \text{end}))))$
- ▶  $W_3 = \text{diag}(V_3) / \text{mean}(\text{diag}(V_3))$

# Model selection

- ▶ Residuals  $\hat{\beta} - \beta^* = \hat{\beta} - P(\lambda_1, \lambda_2, K)\hat{\beta} = (I - P(\lambda_1, \lambda_2, K))\hat{\beta}$
- ▶ Analog of residual degrees of freedom:  $\text{trace}(I - P(\lambda_1, \lambda_2, K))$
- ▶ Analog of model degrees of freedom:  $\text{df}(\lambda_1, \lambda_2, K) = \text{trace}(P(\lambda_1, \lambda_2, K))$
- ▶ Choose  $\beta^*$  that minimizes BIC analog (over pre-specified grid) :  
 $Q(\beta^*, \lambda_1, \lambda_2, K) + \log(H)\text{df}(\lambda_1, \lambda_2, K)$

# Post-selection Inference

Consider CIs of the form  $\{\ell_h(X), u_h(X)\}_{h=1}^H = \hat{\beta}_M \pm C^\alpha \sigma_\beta$ .

For  $\alpha = 0.05$ :

- ▶ pointwise CIs:  $\hat{\beta}_M = \hat{\beta}$ ,  $C^\alpha = 1.96$
- ▶ sup-t CIs:  $\hat{\beta}_M = \hat{\beta}$ ,  $C^\alpha$  “sup-t constant”
- ▶ POSI CIs:  $\hat{\beta}_M = \hat{\beta}_{M(Y)}$ ,  $C^\alpha$  “POSI constant”

# Post-selection Inference

$$\text{POSI CIs: } \{\ell_h(X), u_h(X)\}_{h=1}^H = \hat{\beta}_{M(Y)} \pm C^\alpha \sigma_\beta.$$

For  $\alpha = 0.05$ , let  $C^\alpha$  be the minimal value that satisfies

$$\mathbb{P} \left( \max_{M \in \mathcal{M}} \max_h |t_{h,M}| \leq C^\alpha \right) \geq 0.95$$

- ▶  $t_{j,M}$  denotes the t-ratio for the proxy  $\beta_{M(Y)}$  at horizon  $h$
- ▶  $C^{0.05}$  depends on  $\mathcal{M}$ , the universe of models considered
- ▶  $C^{0.05}$  does not depend on the model selection procedure